# **Echelon Form and Reduce Echelon Form**

#### Definition

A rectangular matrix is in **echelon form** (or **row echelon form**) if it has the following three properties:

- All nonzero rows are above any rows of all zeros. So all rows of only 0's are at the bottom
   Each leading entry of a row is in a column to the right of the leading entry of the row above it.
- 3. All entries in a column below a leading entry are zeros.

If a matrix in echelon form satisfies the following additional conditions, then it is in reduced echelon form (or reduced row echelon form):

- 4. The leading entry in each nonzero row is 1.
- 5. Each leading 1 is the only nonzero entry in its column.

**Example 1** Determine which matrices are in reduced echelon form and which others are only in echelon form.

a. 
$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$
 Reduced echelon form  
b.  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$   
c.  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$  Not echelon. By checking RI and R2, the  
matrix closes not satisfy  $\ddagger 2$  and  $3$   
d.  $\begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$  Echelon form. But not reduced echelon form.

#### Theorem 1 (Uniqueness of the Reduced Echelon Form)

Each matrix is row equivalent to one and only one reduced echelon matrix.

**Question:** Given a matrix A, how to produce a (reduced) echelon matrix that is row equivalent to A? We will answer this question in the rest part of this section. (Row Reduction Algorithm)

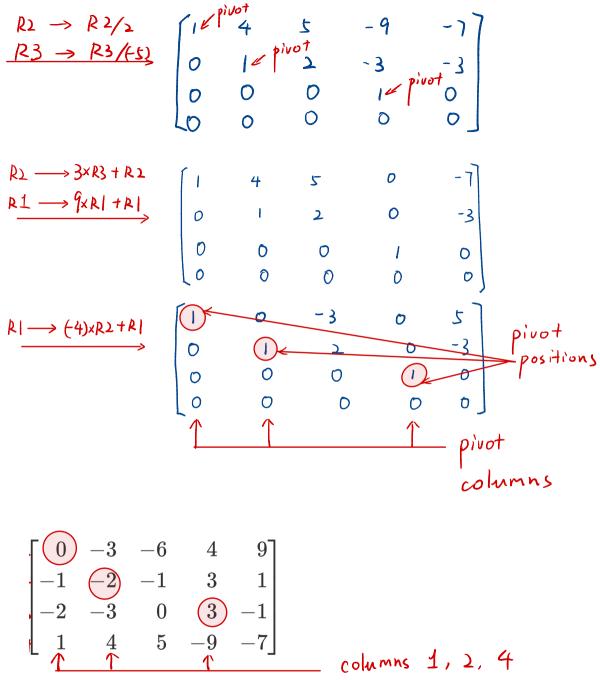
#### **Pivot Positions**

#### Definition

- A **pivot position** in a matrix *A* is a location in *A* that corresponds to a leading 1 in the reduced echelon form of *A*.
- A **pivot column** is a column of *A* that contains a pivot position.

**Example 2** Row reduce the given matrix to reduced echelon form. Circle the pivot positions in the final matrix and in the original matrix, and list the pivot columns.  $p_{1}v_{0}^{\dagger}$ 

| and in the original matrix, a                                   |          |  |                           | s.       | [ ]      |   |
|---|----------|--|---------------------------|----------|----------|---|
| [10 -3 -6]  | 4        | 97   | interchange               | 1º       | 4        | 5 -9 -7]  |
|   |          | 1 RI   | ←→ R4                     | -1       | -2       | -1 3 1  |
| $A = \begin{bmatrix} -1 & -2 & -1 \\ -2 & -3 & 0 \end{bmatrix}$ | 3<br>3 – | $\begin{array}{c c} 1 & \frac{\mathbf{k}}{\mathbf{t}} \\ -1 & \mathbf{t} \\ \mathbf{p} \\ \mathbf{k} \\ k$ | nt l in the<br>t position | -2       | -3       | 0 3 -1  |
| $R_4$ 1 4 5 –   |          | -7   | position                  | 5        |          |   |
| -   |          | -  |                           | Į β<br>↑ | -3       | -6 4 9  |
|   |          | next   | pivot                     | pivot    | column   |   |
|   | [I       | 4  | 5                         | - 9      | -7]      |   |
| RI added to R2<br>2×RI added to R3                              | D        | 2  | 4                         | -6       | -6       |   |
| to create O's below the   | D        | 5  | 10                        | -15      | -15      |   |
| pivot. Choose 2 as the  | 0        | -3   | -6                        | 4        | 9        |   |
| next pivot  | ζ        | Ť  | Sectional                 | 44       | ر        |   |
|   |          | next   | pivot colu                | imn.     | 2        |   |
| -IxR2 added to R3   | $\int I$ | 4  | 5                         | -9       | -7)      |   |
| -1×R2 added to R4   | 0        | 2  | 4                         | -6       | -6       |   |
| to create 0's below the   | 0        | 0  | 0                         | 0        | 0        |   |
| pivot.  | 0        | 0  | 0                         | -5       | D        |   |
|   | $\zeta$  | 4  | ٢                         | -9       | ر<br>[ر_ | Note it is in echelon form.                         |
| interchange   | '        | T  | د                         | 1        | 1        | & Mo process the following                          |
| $R_3 \iff R_4$  | 0        | 2  | 4                         | -6       | -6       | de la set la ponoren g                              |
| to produce a leading<br>entry in column 4.                      | 0        | O  | O                         | -5       | 0        | We process the following<br>steps to get the reduce |
|   | 0        | 0  | 0                         | 0        | ره       | echelon form  |
|   | S        |  |                           |          |          | 1   |



columns 1, 2, 4 are pivot columns With **Example 2**, we are ready to describe an efficient procedure for transforming a matrix into an echelon or reduced echelon matrix:

The Row Reduction Algorithm Step 1-4 are called forward phase

**STEP 1:** Begin with the leftmost nonzero column. This is a pivot column. The pivot position is at the top.

**STEP 2:** Select a nonzero entry in the pivot column as a pivot. If necessary, interchange rows to move this entry into the pivot position.

**STEP 3:** Use row replacement operations to create zeros in all positions below the pivot.

**STEP 4:** Cover (or ignore) the row containing the pivot position and cover all rows, if any, above it. Apply steps 1 to 3 to the submatrix that remains. Repeat the process until there are no more nonzero rows to modify.

**STEP 5:** Backward phase. Beginning with the rightmost pivot and working upward and to the left, create zeros above each pivot. If a pivot is not 1, make it 1 by a scaling operation.

**Example 3** Using the algorithm above, row reduce the given matrix to reduced echelon form.

|        |         | -5   | 4 | 6  | -6 | 3  | Γ0 |
|--------|---------|--|---|----|----|----|----|
|        |         | 9  | 8 | -5 | 8  | -7 | 3  |
| column | _ pivot | $\begin{array}{c} -5 \\ 9 \\ 15 \end{array}$ | 6 | -9 | 12 | -9 |    |
|        | - T     |  |   |    |    |    |    |

**STEP 1:** Begin with the leftmost nonzero column. This is a pivot column. The pivot position is at the top.

**STEP 2:** Select a nonzero entry in the pivot column as a pivot. If necessary, interchange rows to move this entry into the pivot position.

$$\begin{array}{c|c} (-1) \times R \mid \text{ added to } R1 \\ \hline 0 \\ 0 \\ \hline 0 \\ \hline 3 \\ \hline -6 \\ \hline 6 \\ \hline 4 \\ -5 \\ \hline \end{array}$$

**STEP 4:** Cover (or ignore) the row containing the pivot position and cover all rows, if any, above it. Apply steps 1 to 3 to the submatrix that remains. Repeat the process until there are no more nonzero rows to modify.

Next pivot column

Again, we have two options: () Divide R2 by 2 to get 1 in the pivot position. Then add (-3) x R2 to R3

or,  $\Theta$  Add  $(-\frac{3}{2}) \times R_2$  to R3.

2 -6

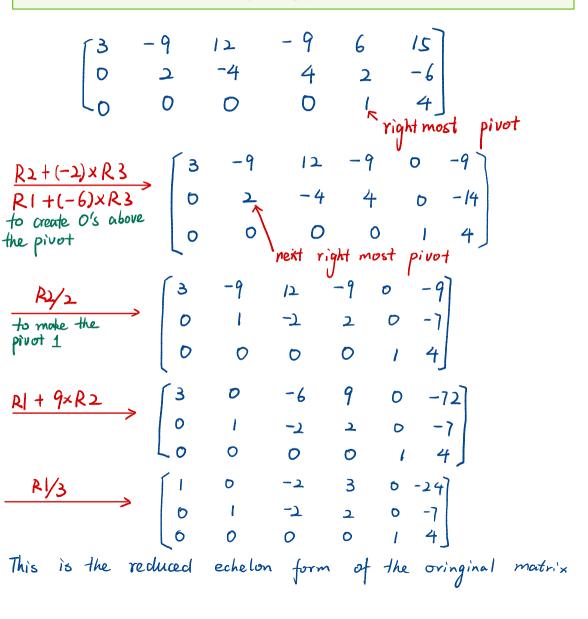
We choose @ in our calculation:

(3 -9 12 -9 6 15 0 2 -4 4 2 -6 0 0 0 0 1-4 pivot, no more rows to modify

So we are done with Step 4. The above matrix is an echelon form (You can double check this with the 3 properties on Page 1)

# If we want the reduced echelon form, we continue with Step 5:

**STEP 5:** Backward phase. Beginning with the rightmost pivot and working upward and to the left, create zeros above each pivot. If a pivot is not 1, make it 1 by a scaling operation.



#### Solutions of Linear Systems

#### Definitions

Basic variable: the variables corresponding to pivot columns in the matrix

Free variable: the other variables

Example 3 The augmented matrix of a linear system has been written in the reduced echelon form as follows

Example 3 The augmented matrix of a matrix of a matrix of a matrix of a matrix. Notice: The system has 3 eqns with 3 varibles by checking  $\begin{bmatrix} 1 & 0 & -5 & 1 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ the size of the matrix. Cohumn 1 and 2 are the basic variable and free variable. The pivot cohumns. Free variable: X3 (2) Find the general solution of the above system. ANS: The corresponding system is  $\begin{cases} X_1 & -5X_3 = 1 \\ X_2 + X_3 & = 4 \end{cases}$ So the solution can be writte as  $\begin{cases} x_1 = 1 + 5 x_3 \\ x_2 = 4 - x_3 \\ x_3 \text{ is free} \end{cases}$ Note: Each different choice of X3 determines a solution to the system, and every solution to the system is determined by a choice of X3

### **Existence and Uniqueness Questions**

#### **Existence and Uniqueness Theorem**

A linear system is consistent if and only if the rightmost column of the augmented matrix is not a pivot columnthat is, if and only if an echelon form of the augmented matrix has no row of the form

 $\begin{bmatrix} 0 & \cdots & 0 & b \end{bmatrix}$  with *b* nonzero

If a linear system is consistent, then the solution set contains either

(i) a unique solution, when there are no free variables, or

(ii) infinitely many solutions, when there is at least one free variable.

**Example 4** Choose h and k such that the system has (a) no solution, (b) a unique solution, and (c) many solutions. Give separate answers for each part.

$$x_{1} + 3x_{2} = 2$$
ANS: The corresponding augmented matrix is
$$3x_{1} + hx_{2} = k$$

$$\begin{pmatrix} 1 & 3 & 2 \\ 3 & h & k \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 3 & 2 \\ 0 & h-9 & k-6 \end{pmatrix}$$
(a) By the Thm above (blue box), the system has no solution
if and only if R2 is of the form  $\begin{bmatrix} 0 & 0 & b \end{bmatrix}^{R^{0}}$ 
i.e.,  $h-9=0 \implies \int_{k=6}^{h=9} \int_{$ 

The following procedure outlines how to find and describe all solutions of a linear system.

# USING ROW REDUCTION TO SOLVE A LINEAR SYSTEM

**1.** Write the augmented matrix of the system.

**2.** Use the row reduction algorithm to obtain an equivalent augmented matrix in echelon form. Decide whether the system is consistent. If there is no solution, stop; otherwise, go to the next step.

**3.** Continue row reduction to obtain the reduced echelon form.

4. Write the system of equations corresponding to the matrix obtained in step 3.

**5.** Rewrite each nonzero equation from step 4 so that its one basic variable is expressed in terms of any free variables appearing in the equation.

# The following question is left as an exercise. I will provide the complete notes for solving them after the lecture.

**Exercise 5** Find the general solutions of the systems whose augmented matrices are given as follows.

| (1) | $\lceil 1 \rceil$ | 4 | 0 | 7  |
|-----|-------------------|---|---|----|
|     | $\lfloor 2$       | 7 | 0 | 11 |

|     | [ 1  | -7  | 0  | 6  | 5] |
|-----|------|---|----|----|----|
| (2) | 0    | 0   | 1  | -2 | -3 |
|     | [-1] | $egin{array}{c} -7 \\ 0 \\ 7 \end{array}$ | -4 | 2  | 7  |

|                | Γ1 | -3 | 0 | -1 | 0  | -2] |
|----------------|----|----|---|----|----|-----|
| $(\mathbf{a})$ | 0  | 1  | 0 | 0  | -4 | 1   |
| (3)            | 0  | 0  | 0 | 1  | 9  | -4  |
|                | 0  | 0  | 0 | 0  | 0  | 0   |

ANS:

$$(1) \begin{bmatrix} 1 & 4 & 0 & 7 \\ 2 & 7 & 0 & 11 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & 0 & 7 \\ 0 & -1 & 0 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & 0 & 7 \\ 0 & 1 & 0 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & -5 \\ 0 & 1 & 0 & 3 \end{bmatrix}$$

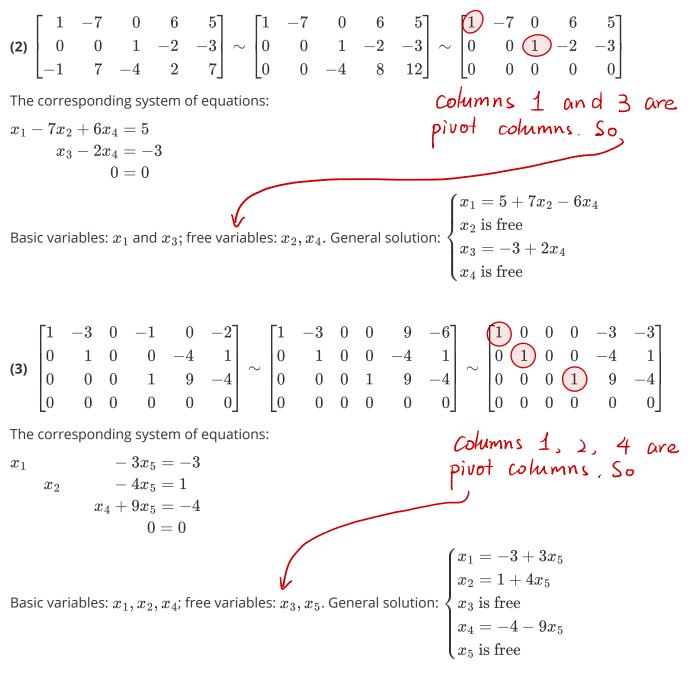
The corresponding system of equations:

 $egin{array}{ll} x_1=-5\ x_2=3 \end{array}$ 

The basic variables (corresponding to the pivot positions) are  $x_1$  and  $x_2$ . The remaining variable  $x_3$  is free. Solve for the basic variables in terms of the free variable. In this particular problem, the basic variables do not depend on the value of the free variable.

General solution:  $\begin{cases} x_1 = -5 \ x_2 = 3 \ x_3 \text{ is free} \end{cases}$ 

**Remark**: A common error in Exercise 5 (1) is to assume that  $x_3$  is zero. To avoid this, identify the basic variables first. Any remaining variables are free. (This type of computation will arise in Chapter 5.)



**Remark**: The *Study Guide* discusses the common mistake  $x_3 = 0$ .